

Quasi-Z-Source inverter with hybrid energy storage for IM drive system

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ABSTRACT – This paper investigates on the newly proposed hybrid energy storage system on quasi-Z-source inverter (qZSI) for the induction motor (IM) drive system. The objectives are to reduce the current stress on the battery with supercapacitor hybrid energy storage based on bidirectional DC/DC converter. The performance of the field-oriented control (FOC) for IM drive and proposed method of hybrid energy storage system during acceleration/regenerative braking is evaluated by time-domain simulation in MATLAB/Simulink environment. The results verify the benefit of qZSI converter and proposed method works satisfactorily according to the requirement to reduce the battery current stress, thus increasing the efficiency of the overall system

1. INTRODUCTION

As the electrical vehicle (EV) is operating in various condition including high power transient during the acceleration and regenerative braking, it requires the energy storage system (ESS) to function as an energy buffer and backup for the system [1]. The effect of transient power during high speed operation, due to the regenerative braking of the motor may cause an enormous damage to the battery due to its low power density. The supercapacitor (SC) on the other side has a higher power density, and capable of charge/discharge at faster rate. In order to utilize the supercapacitor to its maximum, the DC/DC converter must have an efficient control of the power flow, which can further improve the system. On the inverter/drive side, quasi-Z-source inverter (qZSI) topology has gained attention as an alternative to boost the DC bus voltage [2-3] and overcomes the output voltage constraints of the conventional drives. Moreover, the qZSI also demonstrates fault-tolerant capabilities to shoot-through faults and voltage sags [4]. This work proposes on the new method of installing a secondary energy storage to realize hybrid energy storage system (HESS) based on battery and SC for the qZSI fed motor drive system.

2. METHODOLOGY

Figure 1 shows the overall block diagram of the qZSI based IM drive system with hybrid energy storage. The battery as a primary energy source, while supercapacitor as a secondary energy source connected in parallel to capacitor C_1 via a bidirectional DC-DC converter. The diode in qZSI is replaced with IGBT switch S_7 to enable a bidirectional power flow from/into the battery. The bidirectional DC-DC converter functions as a boost/buck converter during forward/braking operation. A

dSpace1104 microcontroller platform is used to process the measured signals and producing the switching signals. Table 1 and Table 2 show the parameters values and specification of the overall system.

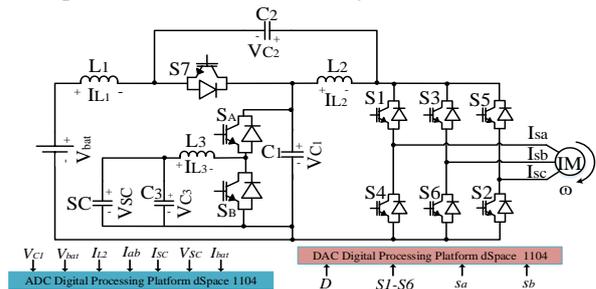


Figure 1 qZSI based IM drive with hybrid energy storage.

Table 1 qZSI and energy storage system parameters.

Parameters	Values
Battery Capacity	Lead acid 30units x 12V (nominal 360V,42 Ah)
Supercapacitor	400F, 134 units x 2.7V
Bidirectional DC-DC Converter	$L_3 = 10 \text{ mH}$, $C_3 = 220 \text{ uF}$
Switching Freq.	10 kHz
qZSI network	$L_1 = L_2 = 4.7 \text{ mH}$, $C_1 = C_2 = 1000 \text{ uF}$

Table 2 Induction Motor (IM) parameters.

Parameters IM	Values
Rated voltage and current	360V, 3.5 A
Rated speed	1450 rpm
Rated frequency	50 Hz
Inertia (J), Friction factor (B)	$J = 0.02 \text{ kgm}^2$, $B = 0.001 \text{ Nm/rad}$
Stator and Rotor inductance	$L_s = 0.3252 \text{ H}$, $L_r = 0.244 \text{ H}$
Mutual inductance	$L_m = 0.3117 \text{ H}$
No. pole pair	2
Stator and Rotor resistance	$R_s = 3.45 \text{ } \Omega$, $R_r = 3.4 \text{ } \Omega$

2.1 Field Oriented Control of IM and Dual loop Capacitor Voltage Control of qZSI

A dual loop capacitor voltage control is applied in this work by controlling the capacitor C_1 voltage at a fixed value to keep a balance power transfer between the energy source and the IM drive [4]. As shown in Figure 2(a), PI controller is used to control V_{C1} and inductor current I_{L2} to produce the shoot-through duty ratio d . On the motor drive side, the field-oriented control (FOC) is applied to the induction motor aims at obtaining a decoupled control of the machine flux and torque by referring the (α, β) machine model to a rotating (d, q)

